



## Simple Random Walks in the plane:

### An energy based approach

### Part IV : Variable Fortunes

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In this FourthPart, we investigate the case of variable barriers : the barrier is represented by a function of time; say for instance  $b(n) = \pm\sqrt{n}$ .

We consider symmetric barriers, which means that the rules are the same for both players: if at some time  $n$  the fortune of one of the players reaches the barrier, the game stops. The question is: what is the probability that the game continues after  $N$  steps and, more precisely, what is the probability of the fortune of each player (what we call "profile" of fortune) ?

The main theorem is as follows:

**Theorem.** - The probability  $E_n$  that the game continues after  $n$  steps tends to 0 when

$N \rightarrow +\infty$  if and only if the integral  $\int \frac{dx}{b^2(x)}$  diverges at  $+\infty$ . More precisely, this proba-

bility satisfies the estimate:

$$E_n \leq \exp \left( -\frac{\pi^2}{16} \int_1^{t_{n+1}} \frac{dx}{b^2(x)} \right)$$

where  $t_n$  is the unique number such that  $b(t_n) = n$ .

During the  $n^{\text{th}}$  period (see definition below), the profile of fortune is proportional to the vector:

$$(\sin(\vartheta), \sin(2\vartheta), \dots, \sin(n\vartheta), \sin((n-1)\vartheta), \dots, \sin(\vartheta))$$

where  $\vartheta = \frac{\pi}{2n+1}$ .

The case of the barrier  $f(n) = \pm \sqrt{n \text{Log}(n)}$  is of special interest, because it lies above Khinchine's safety curve  $\varphi(n) = \sqrt{2n \text{Log}(\text{Log}(n))}$ . Still, the main Theorem shows that the probability that the game continues after  $N$  steps tends to 0 when  $N \rightarrow +\infty$ , and gives quantitative estimates for this probability.

We use the "energy based" approach, described in Parts 1 and 2.

# I. Transition between two periods

## 1. Energy propagation

For us, a "barrier" will be a positive function  $b(x)$ , defined on  $x \geq 0$ , differentiable, increasing, and satisfying  $b(x) \rightarrow +\infty$  when  $x \rightarrow +\infty$ . A simple example is  $b(x) = \sqrt{x}$ .

We have a continuous barrier, but our game uses only integer values. So we have to convert our barrier into a succession of constant segments, with integer values.

Let us describe this representation in detail in the case of the barrier  $\pm\sqrt{n}$ .

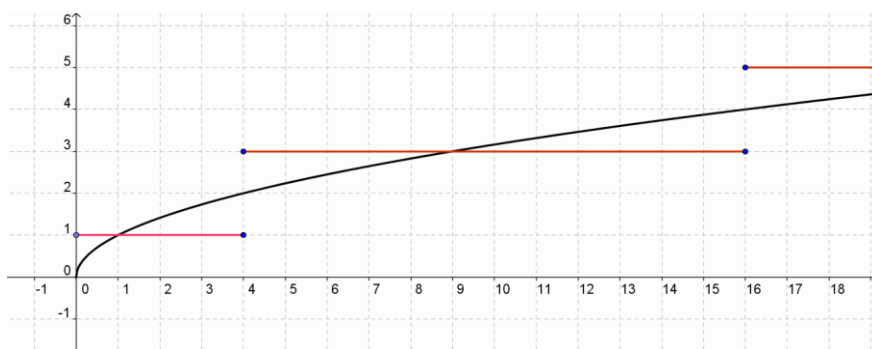


Figure 1.1: discretization of the barrier

The changes will occur at times  $4n^2$ ,  $n = 0, 1, \dots$ . On the interval  $4n^2 \leq x < 4(n+1)^2$ , the barrier is at  $2n+1$  (recall from Part II that we want even values of time and odd values for the barrier). So, in the notation introduced in Part II,  $\xi = n$  and this value is used on an interval of length  $l_n = 4(n+1)^2 - 4n^2$ , that is  $l_n = 8n + 4$ .

The interval of time during which  $\xi = n$  is called the  $n^{\text{th}}$  period. From now on, we forget about the continuous curve and remember only the segments.

We have now to investigate the transition between two periods. The barrier was at  $2\xi + 1$  and moves to  $2\xi + 3$ .

Let us first consider the transition on the energy, that is the variables  $e(2n, 2k)$  (see Part II).

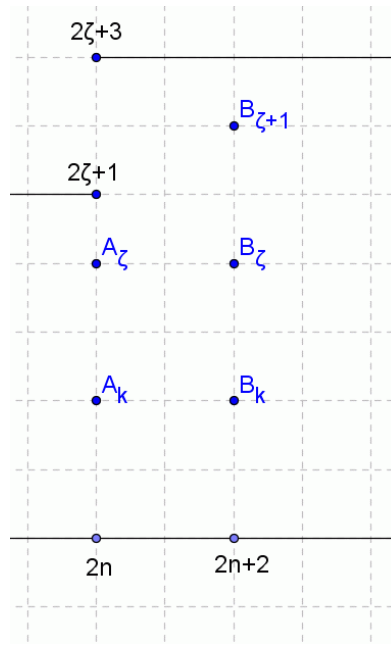


Figure 1.2 : Notation for the transition

It will be convenient to have a simple notation just for the transition. On the vertical corresponding to time  $2n$ , we have  $\xi + 1$  points  $A_0, \dots, A_\xi$ ; at time  $2n + 2$ , we have  $\xi + 2$  points  $B_0, \dots, B_{\xi+1}$ . We denote by  $a_k$  the energy at the point  $A_k$  and similarly  $b_k$  for the  $B_k$ .

For the first  $\xi$  points, we have the usual transition equations:

$$b_0 = \frac{1}{2}(a_0 + a_1) \quad (1.1)$$

$$b_k = \frac{1}{4}a_{k-1} + \frac{1}{2}a_k + \frac{1}{4}a_{k+1} \text{ for } k = 1, \dots, \xi - 1 \quad (1.2)$$

The last two equations are different from the constant case; they are:

$$b_\xi = \frac{1}{4}a_{\xi-1} + \frac{1}{2}a_\xi \quad (1.3)$$

$$b_{\xi+1} = \frac{1}{4}a_\xi \quad (1.4)$$

If the barrier was constantly at  $2\xi + 1$ , instead of (1.3), we would have:

$$b_\xi = \frac{1}{4}a_{\xi-1} + \frac{1}{4}a_\xi \quad (1.5)$$

and instead of (1.4) :

$$b_{\xi+1} = 0 \quad (1.6)$$

So, the fact that the barrier moves one step higher means that less energy is lost:

- for  $b_\xi$ , increase of  $\frac{1}{4}a_\xi$
- for  $b_{\xi+1}$ , increase of  $\frac{1}{4}a_\xi$

which represents a total increase of energy equal to  $\frac{1}{2}a_\xi$ .

Let us now turn to the variables  $x(n, k)$  and describe the transition on these variables. Recall that, for  $k = 0, \dots, \xi - 1$  and  $n \geq 2$ :

$$x_k = \frac{1}{2}(a_k + a_{k+1})$$

We have (see Part II):

$$b_0 = x_0 \quad (1.7)$$

$$b_k = \frac{1}{2}(x_{k-1} + x_k) \text{ for } k = 1, \dots, \xi - 1 \quad (1.8)$$

$$b_\xi = \frac{1}{4}(a_{\xi-1} + a_\xi) + \frac{1}{4}(a_\xi + a_{\xi+1}) \text{ with } a_{\xi+1} = 0$$

which gives:

$$b_\xi = \frac{1}{2}x_{\xi-1} + \frac{1}{2}x_\xi \quad (1.9)$$

$$b_{\xi+1} = \frac{1}{4}(a_\xi + a_{\xi+1}) = \frac{1}{2}x_\xi \quad (1.10)$$

Let us define  $y_k = \frac{1}{2}(b_k + b_{k+1})$ ,  $k = 0, \dots, \xi$ .

We get:

$$y_0 = \frac{1}{2}\left(x_0 + \frac{1}{2}(x_0 + x_1)\right) = \frac{3}{4}x_0 + \frac{1}{4}x_1$$

$$y_k = \frac{1}{4}(x_{k-1} + 2x_k + x_{k+1}), \quad k = 1, \dots, \xi - 1$$

$$y_\xi = \frac{1}{2}\left(\frac{1}{2}x_{\xi-1} + \frac{1}{2}x_\xi + \frac{1}{2}x_\xi\right) = \frac{1}{4}x_{\xi-1} + \frac{1}{2}x_\xi$$

The equations are the same as in the constant case; we simply have one more intermediate equation.

With the original notation, we have:

$$\begin{cases} x(n+1,0) = \frac{3}{4}x(n,0) + \frac{1}{4}x(n,1) \\ x(n+1,k) = \frac{1}{4}x(n,k-1) + \frac{1}{2}x(n,k) + \frac{1}{4}x(n,k+1), \text{ for } k = 1, \dots, \xi-1 \\ x(n+1,\xi) = \frac{1}{4}x(n,\xi-1) + \frac{1}{2}x(n,\xi) \end{cases} \quad (1.11)$$

We have proved:

**Proposition 1.1** - *On the variables  $x(n,k)$ , the fact that the barrier is shifted one step higher leads simply to a new intermediate equation in the transition equations.*

This is quite important in practice, because it means that the theory developed in Part II will apply, despite the changes of position for the barrier. We have simply to take into account the fact that the matrix  $M_n$  will increase by one dimension at the transition between two periods and the corresponding eigenvalues will change accordingly.

We note here that this result applies to any transition, where the barrier is shifted one step up, and does not depend on the particular function  $b(x)$ .

## 2. Changes in the eigenvalues and in the eigenvectors

We now work constantly on the variables  $X_n = x(n,i)$ . In dimension  $\xi$ , we know (see Part II) that the eigenvalues are of the form:

$$\lambda_j = \frac{1 + \cos(\mathcal{G}_{\xi,j})}{2}, \quad \mathcal{G}_{\xi,j} = \frac{2j-1}{2\xi+1}\pi, \quad j = 1, \dots, \xi,$$

and the same expressions will remain in dimension  $\xi+1$ , with  $\xi$  replaced by  $\xi+1$ .

In dimension  $\xi$ , the eigenvectors were:

$$V_{\xi,j} = \left( \sin(\xi \mathcal{G}_{\xi,j}), \dots, \sin(\mathcal{G}_{\xi,j}) \right), \quad j = 1, \dots, \xi$$

and in dimension  $\xi+1$ , they will be:

$$V_{\xi+1,j} = \left( \sin((\xi+1)\mathcal{G}_{\xi+1,j}), \sin(\xi \mathcal{G}_{\xi+1,j}), \dots, \sin(\mathcal{G}_{\xi+1,j}) \right), \quad j = 1, \dots, \xi+1.$$

The natural embedding from dimension  $\xi$  to dimension  $\xi + 1$  (simply adding a zero as the last coordinate) preserves the eigenvectors. Indeed, we have:

**Proposition 2.1.** - *The image of the vector  $V_{\xi,j} = (\sin(\xi\mathcal{G}_{\xi,j}), \dots, \sin(\mathcal{G}_{\xi,j}), 0)$ , with  $\mathcal{G}_{\xi,j} = \frac{2j-1}{2\xi+1}\pi$ , by the matrix  $M_{\xi+1}$  is the vector:*

$$M_{\xi+1}V_{\xi,j} = \left( \lambda_{\xi,j} \sin(\xi\mathcal{G}_{\xi,j}), \dots, \lambda_{\xi,j} \sin(\mathcal{G}_{\xi,j}), \frac{1}{4} \sin(\mathcal{G}_{\xi,j}) \right)$$

and we have  $|M_{\xi+1}V_{\xi,j}|_1 = |V_{\xi,j}|_1$ .

### Proof of Proposition 2.1

This is obvious for the first coordinates, so we have to look only at the last 3. The image of 0 (last coordinate) is  $\frac{1}{4} \sin(\mathcal{G}_{\xi,j})$ . The image of  $\sin(2\mathcal{G}_{\xi,j})$  is  $\lambda_{\xi,j} \sin(2\mathcal{G}_{\xi,j})$ . The image of  $\sin(\mathcal{G}_{\xi,j})$  is by definition  $\frac{1}{4} \sin(2\mathcal{G}_{\xi,j}) + \frac{1}{2} \sin(\mathcal{G}_{\xi,j}) = \sin(\mathcal{G}_{\xi,j}) \left( \frac{1 + \cos(\mathcal{G}_{\xi,j})}{2} \right) = \lambda_{\xi,j} \sin(\mathcal{G}_{\xi,j})$ .

The assertion on the  $l_1$  norm is obvious, since there is no loss of energy in the transition.

This proves Proposition 2.1.

The matrix  $M$ , at any stage, operates only on three coordinates (and only on 2, at the first and last coordinates). So, if these three coordinates are those of an eigenvector of a previous situation, the result is a multiplication by the corresponding eigenvalue.

We now turn to the main Theorem: Let  $b(x)$  be a barrier. We investigate the question: when does the game continue indefinitely?

## II. Main results

### A. Statements of the results

**Theorem. 1** - *The probability  $E_n$  that the game continues after  $n$  steps tends to 0 when*

*$n \rightarrow +\infty$  if and only if the integral  $\int \frac{dx}{b^2(x)}$  diverges at  $+\infty$ . More precisely, this probability satisfies the estimate:*

$$E_n \leq \exp\left(-\frac{\pi^2}{16} \int_1^{t_{n+1}} \frac{dx}{b^2(x)}\right) \quad (1)$$

where  $t_n$  is the unique number such that  $b(t_n) = n$ .

### B. Proof of Theorem 1, first part

First, we will show that if the probability tends to 0, the integral diverges.

#### 1. Converting the integral to a series

We have to convert a statement given in terms of integral into a statement given in terms of a series. This is done by means of the following Proposition.

**Proposition 2** - Let  $b(x)$  be a barrier, that is a positive, differentiable, strictly increasing function, tending to  $+\infty$  when  $x \rightarrow +\infty$ . Let, for each  $n$ ,  $[t_n, t_{n+1}[$  be the interval on which the discretization of  $b$  takes the value  $n$  (this is the  $n^{\text{th}}$  period), and let  $l_n = t_{n+1} - t_n$  be the

duration of this period. Then the integral  $\int_A^{+\infty} \frac{dx}{b^2(x)}$  diverges at infinity if and only if the

series  $\sum_{n=1}^{+\infty} \frac{l_n}{n^2}$  diverges. More precisely:

$$\sum_{n=1}^{+\infty} \frac{l_n}{n^2} = \int_A^{+\infty} \frac{dx}{b^2(x)} \text{ with } A = b^{-1}(1)$$

#### Proof of Proposition 2

Let  $\beta = b^{-1}$  be the inverse function of the function  $b$  (this inverse exists since  $b$  is strictly increasing). It is also positive, differentiable and strictly increasing. We have, by definition  $t_n = \beta(n)$  and therefore:

$$l_n = t_{n+1} - t_n = \beta(n+1) - \beta(n) \approx \beta'(n) = \frac{1}{b'(t_n)}.$$

So we may write:

$$\sum_{n=1}^{+\infty} \frac{l_n}{n^2} \approx \sum_{n=1}^{+\infty} \frac{1}{n^2 b'(t_n)} \approx \int_1^{+\infty} \frac{1}{y^2 b'(\beta(y))} dy$$



Set  $y = b(x)$ ,  $dy = b'(x)dx$ . The above integral becomes:

$$\int_1^{+\infty} \frac{1}{y^2 b'(\beta(y))} dy = \int_A^{+\infty} \frac{b'(x)}{b^2(x) b'(x)} dx = \int_A^{+\infty} \frac{dx}{b^2(x)}, \text{ with } A = b^{-1}(1).$$

which proves Proposition 2.

## 2. Estimates on the energy

**Proposition 3** - *The energy left at the end of the  $N^{\text{th}}$  period satisfies:*

$$E_N \leq \exp\left(-\frac{\pi^2}{16} \sum_{n=2}^N \frac{l_n}{n^2}\right)$$

### Proof of Proposition 3

As we did earlier, we work on the variable  $X_n$  rather than on the energy directly.

The first step is somewhat arbitrary. We should not put the first barrier at  $\xi = 1$  because in this case the game stops immediately. Let us decide that we first introduce the barrier at altitude  $\xi_1 = 64$ , so in general  $\xi_n = n + 63$  and  $t_n$  is the time such that  $b(t_n) = \xi_n$ .

On the interval  $[t_n, t_{n+1}]$ , the barrier takes the value  $\xi_n$ ; the duration of this period is  $l_n$ .

On the original setting, this corresponds to a barrier at  $2n + 1$  on the interval  $[2t_n, 2t_{n+1}]$ .

At time  $t_1$  the energy 1 at O becomes the vector  $X_1$  with components:

$$x(t_1, i) = \frac{1}{2^{2t_{64}}} \begin{pmatrix} 2t_1 + 1 \\ t_1 + i \end{pmatrix} \quad (3.1)$$

The total amount of energy is still 1: there is no loss during the first  $t_1$  steps.

Let  $M$  be the operator reflecting the propagation of energy. It operates first on a space of dimension  $\xi_1$ , then  $\xi_1 + 1$ , and so on.

Now, the vector  $X_1$  does not have a satisfactory shape, in the sense that we have no information at all on the iterates  $M^n X_1$ ; we have such an information only for the eigenvectors of the matrix  $M$  (and these eigenvectors depend on the dimension, of course). Therefore,

we want to replace  $X_1$  by the vector  $V_{1,1}$ , first eigenvector of the matrix  $M$  in dimension  $\xi_1$ . We know that:

$$V_{1,1} = \frac{2(\sin(\xi_1 \mathcal{G}_{1,1}), \dots, \sin(\mathcal{G}_{1,1}))}{\tan(\xi_1 \mathcal{G}_{1,1})} \quad (3.2)$$

with  $\xi_1 = 64$ ,  $\mathcal{G}_{1,1} = \frac{\pi}{2\xi_1 + 1}$ . This vector is normalized in  $l_1$  norm : it has positive coefficients, with sum equal to 1.

The replacement of the vector  $X_1$  by  $V_{1,1}$  is done, using the following Lemma :

**Lemma 4.** - For every  $n$ ,  $|M^n X_1|_1 \leq c |M^n V_{1,1}|_1$  with  $c = \frac{\binom{2\xi_1 + 1}{\xi_1 + i}}{2^{2\xi_1} \cos(\mathcal{G}_{1,1})}$ .

#### Proof of Lemma 4

The first coefficient of  $X_1$  is  $x(1,1) = \frac{1}{2^{2\xi_1 + 1}} \binom{2\xi_1 + 1}{\xi_1 + 1}$ . We have  $X_1(i) \leq c V_{n,1}(i)$  for every  $i = 1, \dots, \xi_1$ , with this choice of  $c$ . The operator  $M$  has positive coefficients, so it respects the order : during each period, we will have  $|M^n X_1|_1 \leq c |M^n V_{n,1}|_1$ , because the  $l_1$  norm is simply the sum of all coefficients (the coefficients are positive). This proves Lemma 4.

We now study the first transition.

### 3. First transition

We are now with an eigenvector,  $V_{1,1}$ , of the matrix  $M$  in dimension  $\xi_1$ . Unfortunately, this vector, when we pass to dimension  $n_1 + 1$ , does not become an eigenvector of the next matrix. More precisely (without normalization),

$$V_{1,1} = (\sin(n_1 \mathcal{G}_{1,1}), \dots, \sin(\mathcal{G}_{1,1})) \quad (n_1 \text{ coordinates})$$

becomes, after embedding :

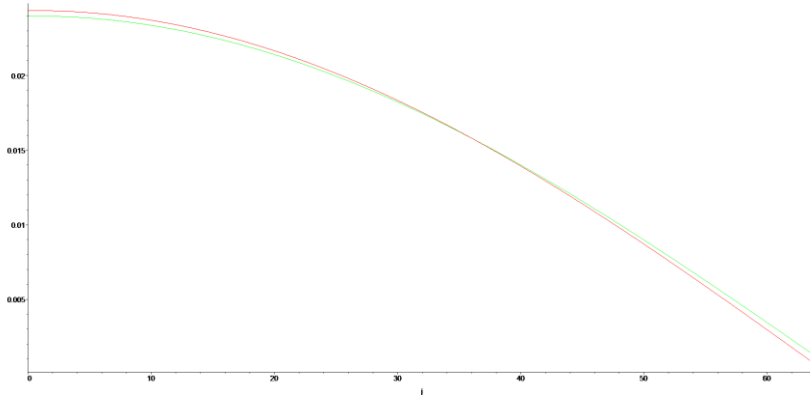
$$V'_{1,1} = (\sin(\xi_1 \mathcal{G}_{1,1}), \dots, \sin(\mathcal{G}_{1,1}), 0) \quad (\xi_1 + 1 \text{ coordinates})$$

whereas the first eigenvector of the new matrix is :

$$V_{2,1} = (\sin((\xi_1 + 1)\mathcal{G}_{2,1}), \dots, \sin(\mathcal{G}_{2,1})) \quad (\xi_1 + 1 \text{ coordinates})$$

$$\text{with } \mathcal{G}_{2,1} = \frac{\pi}{2\xi_1 + 3}.$$

There is no simple connection between  $V'_{1,1}$  and  $V_{2,1}$  : both are very close, as the following picture shows ( $V'_{1,1}$  is in red and  $V_{2,1}$  is in green) :



Still, we cannot simply say that we replace  $V'_{1,1}$  by  $V_{2,1}$ , because  $V_{2,1}$  is slightly closer to the barrier. We may compute the loss in this replacement, but the sum of such losses, over all transitions, is infinite, so such an approach, keeping only one eigenvector at each step, must be abandoned: we have to keep all eigenvectors.

First, what we do is to expand  $V'_{1,1}$  on the basis of eigenvectors of the matrix  $M_2$  in dimension  $\xi_2$ . We describe the general stage of the process.

#### 4. General transition

We will go from dimension  $\xi - 1$  to dimension  $\xi$ . In order to simplify the notation, we denote by  $V_i$  the eigenvectors in dimension  $\xi - 1$  ( $i = 1, \dots, \xi - 1$ ) and by  $W_j$  the vectors in dimension  $\xi$  ( $j = 1, \dots, \xi$ ). Also in order to simplify the notation, we identify  $V_i$  and  $V'_i$  (one more coordinate, equal to 0).

We have the decomposition on the basis of eigenvectors in dimension  $\xi$  :

$$V_i = \sum_{j=1}^{\xi} \alpha_{i,j} W_j = \sum_{j=1}^{\xi} \frac{\langle V_i, W_j \rangle}{|W_j|_2} W_j = \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \sum_{j=1}^{\xi} \langle V_i, W_j \rangle W_j \quad (4.1)$$

In this decomposition, some coefficients are negative, so they do not represent an "energy" in the previous sense of the word. Still, the above decomposition is valid, and represents an algebraic (Hilbert space) decomposition, in which the total energy is the sum of all

components of all vectors. There is a conceptual difficulty here, because we have to leave the framework of "ordinary energy" (every component is positive), and to adopt the framework of "algebraic energy" (some components may be negative).

We introduce a notation for the sum of components of a vector :

$$s(V_i) = \sum_{l=1}^{\xi-1} V_i(l)$$

and the same for  $s(W_j)$ .

With this notation, the total energy at the beginning of the  $\xi^{th}$  period (just after the embedding  $\xi-1 \rightarrow \xi$ ) is :

$$E_\xi = \sum_{i=1}^{\xi-1} s(V_i) \tag{4.2}$$

which may be written:

$$\begin{aligned} E_\xi &= \sum_{i=1}^{\xi-1} s(V_i) = \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \sum_{i=1}^{\xi-1} s\left(\sum_{j=1}^{\xi} \langle V_i, W_j \rangle W_j\right) \\ &= \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \sum_{i=1}^{\xi-1} \sum_{j=1}^{\xi} \langle V_i, W_j \rangle s(W_j) = \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) W_j \right\rangle \end{aligned} \tag{4.3}$$

Let  $l = l_\xi$  be the duration of the  $\xi^{th}$  period, and let  $\lambda_j$ , instead of  $\lambda_{\xi,j}$  ( $j=1, \dots, \xi$ ) be the eigenvalues during this period.

The total energy at the end of the  $\xi^{th}$  period is:

$$F_\xi = \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \sum_{i=1}^{\xi-1} s\left(\sum_{j=1}^{\xi} \langle V_i, W_j \rangle \lambda_j^l W_j\right) \tag{4.4}$$

Indeed, during this period, each  $W_j$  is transformed into  $\lambda_j^l W_j$ . So we have:

$$\begin{aligned} F_\xi &= \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \sum_{i=1}^{\xi-1} s\left(\sum_{j=1}^{\xi} \langle V_i, W_j \rangle \lambda_j^l W_j\right) \\ &= \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \sum_{i=1}^{\xi-1} \sum_{j=1}^{\xi} \langle V_i, W_j \rangle \lambda_j^l s(W_j) = \frac{1}{\frac{\xi}{2} + \frac{1}{4}} \left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) \lambda_j^l W_j \right\rangle \end{aligned}$$

We want to compare  $F_\xi$  and  $E_\xi$ . The following Proposition answers our question and is the key point in our approach.

### 5. Sharp transition estimates

**Proposition 5.** - *The total energy at the end of the  $\xi^{\text{th}}$  period, denoted by  $F_\xi$ , and the total energy at the beginning of the  $\xi^{\text{th}}$  period, denoted by  $E_\xi$ , are linked by the inequality:*

$$F_\xi \leq \lambda_1^l E_\xi$$

where  $l = l_\xi$  is the duration of the  $\xi^{\text{th}}$  period, and  $\lambda_1 = \lambda_{\xi,1}$  is the largest eigenvalue during this period.

#### Proof of Proposition 5

The statement is equivalent to:

$$\left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) \lambda_j^l W_j \right\rangle \leq \lambda_1^l \left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) W_j \right\rangle \quad (5.1)$$

We will study all terms separately.

**Lemma 6.** - *All components of the vector  $\sum_{i=1}^{\xi-1} V_i$  are positive.*

#### Proof of Lemma 6

In dimension  $\xi - 1$ , the components of the  $i^{\text{th}}$  vector,  $V_i$ , are  $\sin((\xi - 1)\mathcal{G}_{\xi-1,i}), \dots, \sin(\mathcal{G}_{\xi-1,i})$ , with  $\mathcal{G}_{\xi-1,i} = \frac{2i-1}{2\xi-1}\pi$ .

The  $k^{\text{th}}$  component (starting from the right) of  $\sum_{i=1}^{\xi-1} V_i$  is therefore  $C_k = \sum_{i=1}^{\xi-1} \sin\left(\frac{k(2i-1)}{2\xi-1}\pi\right)$ .

We use the identity:

$$\sum_{i=1}^{\xi-1} \sin((2i-1)\alpha) = \frac{2\sin(\alpha)(1 - \cos^2((\xi-1)\alpha))}{1 - \cos(2\alpha)}$$

in which we take  $\alpha = \frac{k\pi}{2\xi-1}$ ; since  $1 \leq k \leq \xi$ ,  $0 < \alpha < \frac{\pi}{2}$ , we have  $\sin(\alpha) > 0$ , and this proves Lemma 6.

We now compute the sum of the components of each eigenvector. By definition, it is:

$$s(W_j) = \sum_{k=1}^{\xi} \sin\left(\frac{k(2j-1)}{2\xi+1}\pi\right)$$

**Lemma 7.** - For each  $j=1, \dots, \xi$ , we have:

$$s(W_j) = \frac{\sin \vartheta_{\xi,j}}{2(1-\cos \vartheta_j)} = \frac{\tan(\xi \vartheta_{\xi,j})}{2}, \text{ with } \vartheta_{\xi,j} = \frac{2j-1}{2\xi+1}\pi.$$

**Proof of Lemma 7**

We have the identity, for any  $\vartheta$  and any  $\xi$ :

$$\sum_{k=1}^{\xi} \sin(k\vartheta) = \frac{\sin(\xi\vartheta) - \sin((\xi+1)\vartheta) + \sin(\vartheta)}{2(1-\cos(\vartheta))} \quad (5.2)$$

The numerator is:

$$Num = \sin\left(\xi \frac{(2j-1)\pi}{2\xi+1}\right) - \sin\left((\xi+1) \frac{(2j-1)\pi}{2\xi+1}\right) + \sin\left(\frac{(2j-1)\pi}{2\xi+1}\right)$$

But in fact:

$$\sin\left(\xi \frac{(2j-1)\pi}{2\xi+1}\right) = \sin\left((\xi+1) \frac{(2j-1)\pi}{2\xi+1}\right) \quad (5.3)$$

Indeed, this follows from the equality:

$$\xi \frac{(2j-1)\pi}{2\xi+1} = \pi - (\xi+1) \frac{(2j-1)\pi}{2\xi+1} + 2k\pi \quad (5.4)$$

with  $k = 2j - 2$ .

So we get simply  $Num = \sin\left(\frac{(2j-1)\pi}{2\xi+1}\right)$ . We have finally:

$$s(W_j) = \frac{\sin\left(\frac{(2j-1)\pi}{2\xi+1}\right)}{2\left(1 - \cos\left(\frac{(2j-1)\pi}{2\xi+1}\right)\right)} = \frac{1}{2} \frac{1}{\tan\frac{2j-1}{2\xi+1} \frac{\pi}{2}} = \frac{1}{2} \frac{1}{\tan\frac{\mathcal{G}_j}{2}}$$

which proves Lemma 7.

It follows from Lemma 7 that, since  $j \leq \xi$ ,  $2j-1 \leq 2\xi+1$ , the term  $s(W_j)$  is positive.

We now study the vector  $T = \sum_{j=1}^{\xi} s(W_j)W_j$ .

The  $k^{\text{th}}$  component (starting from the right) is, using Lemma 7:

$$T_k = \sum_{j=1}^{\xi} s(W_j) \sin(k\mathcal{G}_j) = \sum_{j=1}^{\xi} \frac{\sin(k\mathcal{G}_j)}{2 \tan\frac{\mathcal{G}_j}{2}} = \sum_{j=1}^{\xi} \frac{\sin\left(k \frac{2j-1}{2\xi+1} \pi\right)}{2 \tan\frac{2j-1}{2\xi+1} \frac{\pi}{2}}$$

We observe that the coefficient  $\tan\left(\frac{\mathcal{G}_j}{2}\right)$  is positive and increasing with  $j$ .

**Lemma 8.** - For each  $k$ , we have the identity :

$$T_k = \frac{2\xi-1}{4} > 0$$

**Proof of Lemma 8**

Set  $\varphi_j = \frac{2j-1}{2\xi+1} \frac{\pi}{2} = \frac{\mathcal{G}_{\xi,j}}{2}$ . Then :

$$T_k = \frac{1}{2} \sum_{j=1}^{\xi} \frac{\sin(2k\varphi_j)}{\tan(\varphi_j)}$$

We use the identities:

$$\frac{\sin(2kx)}{\tan x} = \frac{1}{2} \left( \frac{\sin((2k+1)x)}{\sin x} + \frac{\sin((2k-1)x)}{\sin x} \right)$$

$$\frac{\sin((2k+1)x)}{\sin x} - \frac{\sin((2k-1)x)}{\sin x} = 4 \cos^2(kx) - 2 = 2(\cos^2(kx) - 1) = 2 \cos(2kx)$$

They give :

$$T_k = \frac{1}{4} \left( \sum_{j=1}^{\xi} \frac{\sin((2k+1)\varphi_j)}{\sin \varphi_j} + \sum_{j=1}^{\xi} \frac{\sin((2k-1)\varphi_j)}{\sin \varphi_j} \right)$$

Set:

$$W_k = \sum_{j=1}^{\xi} \frac{\sin((2k+1)\varphi_j)}{\sin \varphi_j}$$

Then  $T_k = \frac{1}{4}(W_k + W_{k-1})$  and:

$$\frac{\sin((2k+1)\varphi_j)}{\sin \varphi_j} - \frac{\sin((2k-1)\varphi_j)}{\sin \varphi_j} = 2 \cos(2k\varphi_j) = 2 \cos\left(k \frac{2j-1}{2\xi+1} \pi\right)$$

We use the identity  $\sum_{j=1}^{\xi} \cos((2j-1)\vartheta) = \frac{\sin(2\xi\vartheta)}{2\sin(\vartheta)}$ , which gives:

$$W_k - W_{k-1} = \frac{\sin\left(2\xi \frac{k\pi}{2\xi+1}\right)}{\sin\left(\frac{k\pi}{2\xi+1}\right)}$$

But:

$$\sin\left(2\xi \frac{k\pi}{2\xi+1}\right) = (-1)^{k-1} \sin\left(\frac{k\pi}{2\xi+1}\right)$$

and therefore:

$$W_k - W_{k-1} = (-1)^{k-1}$$

Since  $W_0 = \xi$ , this gives:

$$W_{2k} = \xi, \quad W_{2k-1} = \xi - 1$$

$$T_k = \frac{1}{4}(W_k + W_{k-1}) = \frac{2\xi - 1}{4},$$

which proves Lemma 8

Let us now finish the proof of Proposition 5. We want to show that:



$$\left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) \lambda_j^l W_j \right\rangle \leq \lambda_1^l \left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) W_j \right\rangle \quad (5.5)$$

The scalar product on the left hand-side is, by definition:

$$\begin{aligned} \left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) \lambda_j^l W_j \right\rangle &= \sum_{l=1}^{\xi} \sum_{i=1}^{\xi-1} V_i(l) \sum_{j=1}^{\xi} s(W_j) \lambda_j^l W_j(l) \\ &\leq \lambda_1^l \sum_{l=1}^{\xi} \sum_{i=1}^{\xi-1} V_i(l) \sum_{j=1}^{\xi} s(W_j) W_j(l) \\ &= \lambda_1^l \left\langle \sum_{i=1}^{\xi-1} V_i, \sum_{j=1}^{\xi} s(W_j) W_j \right\rangle \end{aligned}$$

since all terms are positive. This finishes the proof of Proposition 5.

## 6. Combining several periods

From Proposition 5 follows that the loss of total energy, during a period of altitude  $\xi$  for the barrier, and duration  $l$ , is  $\leq \lambda_{\xi,1}^l$ , where  $\lambda_{\xi,1}$  is the largest eigenvalue of the matrix  $M$  in dimension  $\xi$ .

Now, during the  $n^{\text{th}}$  period, the altitude of the barrier is  $n$  and the duration of this period is  $l_n$ . The first eigenvalue,  $\lambda_{n,1}$ , satisfies:

$$\lambda_{n,1} = \cos^2\left(\frac{1}{2n+1} \frac{\pi}{2}\right) \approx 1 - \frac{\pi^2}{16} \frac{1}{n^2}$$

The total loss of energy during the  $n^{\text{th}}$  period is  $\leq \lambda_{n,1}^{l_n}$  and the total loss from the beginning

$$\text{is } \leq \prod_{n=1}^N \lambda_{n,1}^{l_n}.$$

So we have:

$$E_N \leq \exp\left(\sum_{n=1}^N \text{Log}(\lambda_{n,1}^{l_n})\right) = \exp\left(\sum_{n=1}^N l_n \text{Log}(\lambda_{n,1})\right) \approx \exp\left(-\frac{\pi^2}{16} \sum_{n=1}^N \frac{l_n}{n^2}\right)$$

But (see Proposition 2):

$$\sum_{n=1}^N \frac{l_n}{n^2} \approx \int_1^{N+1} \frac{dy}{y^2 b'(\beta(y))} = \int_{\beta(1)}^{\beta(N+1)} \frac{dx}{b^2(x)} = \int_1^{t_{N+1}} \frac{dx}{b^2(x)}$$

and finally:

$$E_N \leq \exp \left( -\frac{\pi^2}{16} \int_1^{t_{N+1}} \frac{dx}{b^2(x)} \right)$$

which proves (1).

### C. Theorem 1 - Converse statement

We want to show that if the integral diverges at infinity, the game may continue indefinitely (the remaining energy does not tend to zero). This part is much simpler than the previous one.

First of all, we have seen (Proposition 2 above) that the convergence of the integral is equivalent to the convergence of the series  $\sum_{n=1}^{+\infty} \frac{l_n}{n^2} < +\infty$ .

The energy left after  $N$  periods will be  $E_{t_N} = \exp \left( -\sum_{n=1}^N \frac{l_n}{n^2} \right)$  if we can prove that this energy is carried, during each period, by the first eigenvector of the corresponding matrix.

**Proposition 1.** - We penalize ourselves if, at the end of each period, we replace the first eigenvector of this period by the first eigenvector of the next period, with same normalization.

### Proof of Proposition 1

Let us explain the statement more in detail. Let simply  $V$  be the first eigenvector during the  $n^{\text{th}}$  period. Recall that, when normalized in  $l_1$  norm:

$$V = 2 \tan \frac{\mathcal{G}_1}{2} (\sin(n\mathcal{G}_1), \dots, \sin(\mathcal{G}_1))$$

with  $\mathcal{G}_1 = \frac{\pi}{2n+1}$ ; when we start the  $(n+1)^{\text{st}}$  period, it becomes:

$$V = 2 \tan \frac{\mathcal{G}_1}{2} (\sin(n\mathcal{G}_1), \dots, \sin(\mathcal{G}_1), 0)$$

The first eigenvector of the  $(n+1)^{\text{st}}$  period is:

$$W = 2 \tan \frac{\mathcal{G}_2}{2} (\sin((n+1)\mathcal{G}_2), \dots, \sin(\mathcal{G}_2))$$

with  $\mathcal{G}_2 = \frac{\pi}{2n+3}$ .

When we say that we "penalize ourselves", it means that the energy will be likely to disappear more easily with  $W$  than with  $V$ . So, if we perform this replacement at each step and, at the end, get a non-zero energy, it means that the whole game produces a non-zero energy.

In practice, using Part II, Corollary 3.4, it means that the "tail" of  $W$  contains more energy than the tail of  $V$ ; in simpler terms,  $W$  is closer to the barrier. More precisely, for any  $k \leq n+1$ , let us define the tails made of the last  $k$  terms:

$$V_k = 2 \tan \frac{\mathcal{G}_1}{2} (0, \sin(\mathcal{G}_1), \dots, \sin((k-1)\mathcal{G}_1))$$

$$W_k = 2 \tan \frac{\mathcal{G}_2}{2} (\sin(\mathcal{G}_2), \dots, \sin(k\mathcal{G}_2))$$

in order to prove Theorem 1, second statement, all we need to show is :

**Lemma 2.** – For any  $k$ ,  $k = 1, \dots, n+1$ ,  $|W_k| \geq |V_k|$ .

### Proof of Lemma 2

We use the identity:

$$\sum_{j=1}^k \sin(j\mathcal{G}) = \frac{\sin(k\mathcal{G}) - \sin((k+1)\mathcal{G}) + \sin(\mathcal{G})}{2(1 - \cos(\mathcal{G}))} \quad (1)$$

We have to show that:

$$\tan\left(\frac{\mathcal{G}_1}{2}\right) \frac{\sin((k-1)\mathcal{G}_1) - \sin(k\mathcal{G}_1) + \sin(\mathcal{G}_1)}{1 - \cos(\mathcal{G}_1)} \leq \tan\left(\frac{\mathcal{G}_2}{2}\right) \frac{\sin(k\mathcal{G}_2) - \sin((k+1)\mathcal{G}_2) + \sin(\mathcal{G}_2)}{1 - \cos(\mathcal{G}_2)} \quad (2)$$

Using the identity  $\frac{\tan \frac{t}{2}}{1 - \cos(t)} = \frac{1}{\sin(t)}$ , (2) is equivalent to:

$$\frac{\sin((k-1)\mathcal{G}_1) - \sin(k\mathcal{G}_1) + \sin(\mathcal{G}_1)}{\sin(\mathcal{G}_1)} \leq \frac{\sin(k\mathcal{G}_2) - \sin((k+1)\mathcal{G}_2) + \sin(\mathcal{G}_2)}{\sin(\mathcal{G}_2)} \quad (3)$$

Or:

$$\frac{\sin((k-1)\mathcal{G}_1) - \sin(k\mathcal{G}_1)}{\sin(\mathcal{G}_1)} \leq \frac{\sin(k\mathcal{G}_2) - \sin((k+1)\mathcal{G}_2)}{\sin(\mathcal{G}_2)} \quad (4)$$

Using the identity  $\sin(p) - \sin(q) = 2 \cos \frac{p+q}{2} \sin \left( \frac{p-q}{2} \right)$ , (4) becomes:

$$\cos((2k-1)\mathcal{G}_1) \geq \cos((2k+1)\mathcal{G}_2) \quad (5)$$

But the angles in (5) are smaller than  $\pi$ , so the cosine is decreasing. Therefore, (5) is equivalent to:

$$(2k-1)\mathcal{G}_1 \leq (2k+1)\mathcal{G}_2 \quad (6)$$

That is:

$$\frac{(2k-1)\pi}{2n+1} \leq \frac{(2k+1)\pi}{2n+3} \quad (7)$$

which itself is equivalent to  $4k \leq 4n+2$ , which is satisfied for  $k \leq n$ . For  $k = n+1$ , the  $l_1$  norms are equal by definition. This proves Lemma 2, Proposition 1, and finishes the proof of the Main Theorem.

### III. Examples

A. *The barrier  $b(x) = \pm c\sqrt{x}$*

In this case, the previous results become:

**Theorem 1.** - *Let  $b(x) = \pm c\sqrt{x}$  be the barrier, with  $c \geq 1$ . At the end of the period*

$t_n = \left\lceil \left( \frac{n}{c} \right)^2 \right\rceil$ , *the total energy satisfies:*

$$E_{t_n} \leq \frac{3}{2} n \frac{\pi^2}{8c^2}$$

*In other words, at any instant  $N$ , the energy satisfies:*

$$E_N \leq \frac{3}{2} c \frac{\pi^2}{8c^2} N \frac{\pi^2}{16c^2}$$

The factor  $3/2$  comes (see the estimates (6.2) and (6.3) in Part II) from the conversion of the variable  $X$  to the energy.

B. The barrier  $b(x) = \sqrt{x \text{Log}(x)}$

In this case, we obtain:

**Theorem 2.** - *The energy left after the  $n^{\text{th}}$  period tends to 0 when  $n \rightarrow +\infty$ . More precisely, at the end of the  $n^{\text{th}}$  period, the total energy satisfies:*

$$E_{t_n} \leq \frac{3}{2} (\text{Log}(N))^{\frac{-\pi^2}{16}}$$

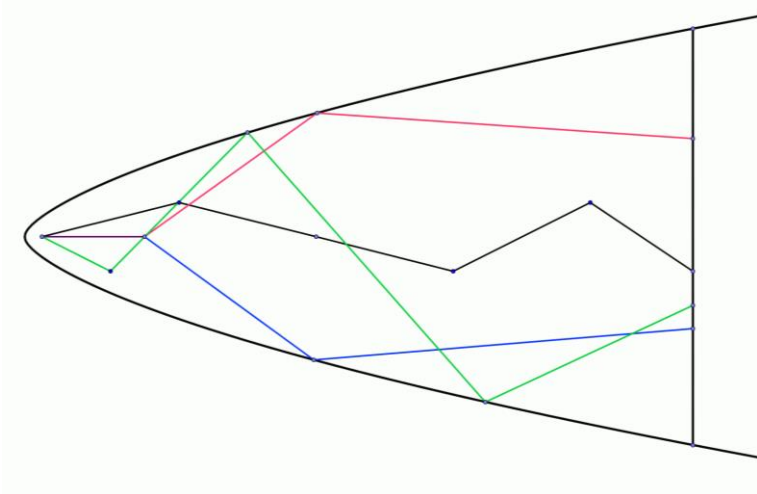
## IV. Energy profile

In all these cases, the energy profile during the  $n^{\text{th}}$  period is approximately proportional to the first eigenvector, and this approximation is more and more accurate when  $n \rightarrow +\infty$ . This means that, during the  $n^{\text{th}}$  period, the energy profile (in the  $X$  variable) is proportional to  $V_n = (\sin(n\mathcal{G}), \dots, \sin(\mathcal{G}))$ , with  $\mathcal{G} = \frac{\pi}{2n+1}$ .

## V. Comparison with Khinchine's curves

Let  $b(x)$  be the barrier ; here  $b(x) = \sqrt{x \text{Log}(x)}$ . Let  $N$  be any instant. The fact that the energy left after the instant  $N$  tends to 0 when  $N \rightarrow +\infty$  may at first sight look contradictory with Khinchine's result, according to which  $k(x) = \sqrt{2x \text{Log}(\text{Log}(x))}$  is a security curve, since our barrier  $b$  is above Khinchine's barrier  $k$ . But in fact, there is no contradiction. Let us explain the situation more in detail.

We distinguish between 4 types of paths (see picture):



$A$  : all paths which never touch  $b$  nor  $-b$  before the instant  $N$  (such a path is drawn in black).

$B^+$  : all paths which touch  $b$  but do not touch  $-b$  before the instant  $N$  (such a path is drawn in red).

$B^-$  : all paths which touch  $-b$  but do not touch  $b$  before the instant  $N$  (such a path is drawn in blue).

$C$  : all paths which touch both  $b$  and  $-b$  before the instant  $N$  (such a path is drawn in green).

Of course, these four sets are disjoint, and their union represents all possible paths.

What we saw, for  $b(x) = \sqrt{x \text{Log}(x)}$ , is that:

$$P(B^+ \cup B^- \cup C) \rightarrow 1 \text{ when } N \rightarrow +\infty.$$

In other words, it becomes more and more unlikely that a path never touches the barrier or its opposite.

This barrier is above Khinchine's security curve, which is:

$$k(x) = \sqrt{2x \text{Log}(\text{Log}(x))}$$

which means that the probability to touch  $b$  after the time  $N$  tends to 0 when  $N \rightarrow +\infty$ . In other words, almost every path returns near Khinchine's curve  $k$  infinitely many times, but this is not so for the barrier  $b$ .

This is not contradictory with our result. It means simply that, for instance :

$$P(B^+) \rightarrow 0.1 \text{ when } N \rightarrow +\infty$$

$$P(B^-) \rightarrow 0.1 \text{ when } N \rightarrow +\infty$$

$$P(C) \rightarrow 0.8 \text{ when } N \rightarrow +\infty$$

So the total probability of hitting  $\pm b$  tends to 1 when  $N \rightarrow +\infty$  (our result), but the probability to hit either  $b$  or  $-b$  after time  $N$  tends to 0 when  $N \rightarrow +\infty$ .